Bringing together the users of Dassault Systèmes PLM solutions - CATIA, ENOVIA, DELMIA, SIMULIA® and 3DVIA®





Brian Prasad, Parker Hannifin/Parker Aerospace Nikhil Shintre, Geometric Limited Jeff Rogers, Parker Hannifin Anurag Jain, Geometric Limited

COE 2010 ANNUAL PLM CONFERENCE A N D T E C H N I F A I R April 18-21, 2010 • The Rio All-Suite Hotel • Las Vegas, Nevada

Founding Partne









## Introduction



- Today's Product Development Environment
  - Multidisciplinary control systems
  - Collaboration across organizations
  - Shrinking timeline & costs

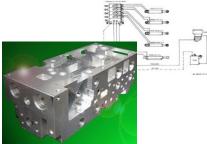
### **Agenda of Session**

- Development of Control System
  - Challenges of packaging
  - Expectations from integrated packaging
- Proposed architecture on CATIA-V5
  - Description of original & dummy problem
  - Use of PowerCopy with OGS
  - Enhancing PCs with KW functions & Automation
- Implementation results & Conclusion

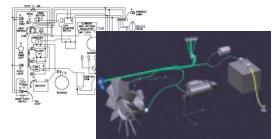


# Packaging of Control System

- New products involve multiple systems Mechanical, Electronics, Hydraulics
- System design defines control flow which is realized by physical design aka Packaging
- Packaging constraints Operating Clearances, Minimum wall thickness, etc.
- Packaging is trial and error process
  - Engineers try different combinations
  - Must retain system integrity
  - Must meet constraints
- Change propagation is tricky
  - System & Packaging association
  - Small change upsets whole packaging



Fluid Control System



Wiring Harness





## **Expectation from Packaging System**



Schematic

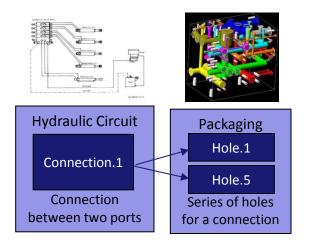


3D Envelope

Ability to freely move the components

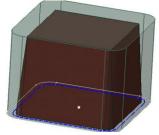
Full 3D Shape

- Manage representations as associative unit
- No hard positioning of components
- Minimal dependencies across components



Manage multiple representations

- Lightweight for quick viewing
- Realistic shape in 3D solid
- Envelope for Operating clearances

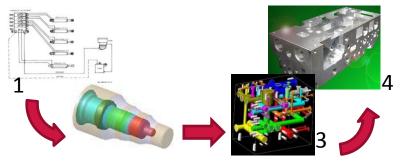


Model with 3 representations

- System & packaging design correspondence
  - Correlate physical connections with a system connection
  - Retain integrity of system design, while breaking / merging physical connections
  - Allow change of components with minimal impact on connections



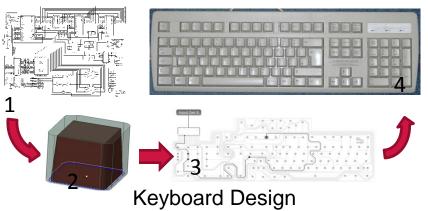
## **Problem Description**



Fluid Control Design 1. Hydraulic Circuit, 2. Creation of components & connections 3. Positioning of components & connections, 4. Block Manifold

#### **Overview**

- Original Problem Fluid Control System
- Dummy Problem Design of keyboard



1. Electronic System Design, 2. Creation of keys & connections 3. Positioning keys & connections, 4. Design of keyboard body

#### **Dummy Problem - Keyboard Design**

- Electronic system design
- Creation of keys & connections
- Packaging
  - Placement of components (i.e. key)
  - Routing of connections
- Design of keyboard body & enclosures



## **Design Context**

•





### Part OR Product Environment

- Both part & product can meet requirement
- Part environment is preferred
  - Eases break / merge connections in routing
  - Allows assembling of all bodies for enclosure design
- In Part environment, Key & Connection are represented by templates

### **UDF OR PowerCopy Template**

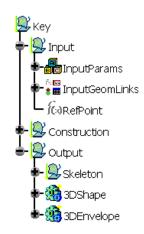
- UDF creates single unit for all three representations
- PowerCopy (PC) is chosen over UDF
  - Allows to activate / deactivate 3 different representations
  - No special license requirements
- PC will replicate all template entities, when instantiated. This must be managed properly.



# Managing PowerCopy

- Content of PowerCopy
  - Construction geometries
  - Output Skeleton
  - Output Full 3D Shape
  - Output Envelope
  - Knowledgeware entities
- PowerCopy MUST be managed in single container for
  - Deleting / Replacing
  - Manipulating as single unit
- Only 'Ordered Geometrical Set (OGS)' can contain all types

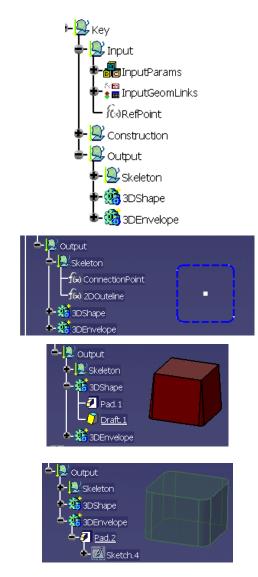
	GS	OGS	Body
Geometrical Set (GS)	Х		Х
Ordered Geometrical Set (OGS)		Х	Х
Body		Х	
Knowledgeware Entities		V	
(Parameters, Relations)		X	
Solid features			Х
Point, Wire / Sketch, Surface	Х	Х	Х
Volumes	Х	Х	





# Structure of Key PowerCopy

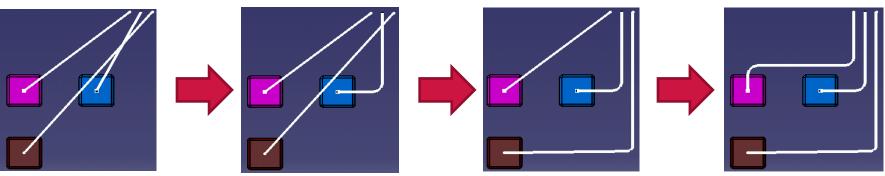
- Inputs
  - Dimension parameters and control flags
  - KW Parameters linked to positioning point
- Construction
  - Support planes, Reference lines, etc
  - Sketch forming the shape of key
- Output
  - Skeleton Connection point & Lightweight outline
  - 3D Shape Key shape with pad / draft
  - 3D Envelope Sketch offset and pad





# Structure of Connection PowerCopy

- Inputs
  - Dimension parameters and control flags
  - KW Parameters linked to inputs Start / End and other points on path
- Construction
  - Polyline passing through the points
  - Profile sketch controlled through parameters
- Output
  - Skeleton Polyline representing connection path
  - 3D Shape Sweep using the profile and polyline
  - 3D Envelope Sweep with clearance to maintain minimum gap





COE 2010 ANNUAL PLM CONFERENCE AND TECHNIFAIR April 18-21, 2010 • The Rio All-Suite Hotel • Las Vegas, Nevada

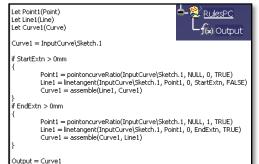
## **Demo - Key / Connection Manipulation**

CATIA V5 - [Copy					
<u>Start File E</u> dit	View Ins	ert <u>T</u> ools	Window	Help	
PartBody					
Point.2					
-бх -бү -бг					
<b>-</b> @ γ					Γ
L∰z					
Point.8					Ĺ
- Фх - Фу - Фу					
-⊜Y					
🕈 🍯 Point.9					
🕈 📲 Point.10					
🔶 - Point.13					
Point.14					
Key.1					
1. Input					
Construction					
A Soutput					
Key.2					
🕂 🏝 Input					
Construction					
- Output					
Connection.1					
Point.11					
Polyline.1					
Connection.2					
Point.12					
-@)× -@)γ -@)z					
- 🗗 Y					
L D Z					
Polyline.3					
Key.3					
🕈 🛃 Input					
+ Dutput					
Connection.3					
+ Point.17					
Point.18					



## Scalability of PowerCopy





Description	Size of 5 PC instances	Time to update
GSD Approach	111 kB	2.29 sec
Rule Approach	61 kB	0.81 sec

#### **Scalability Issues**

- Increasing no of PCs increases the file size and degrades the performance.
- Users complain slow system response, which affects speed of work.

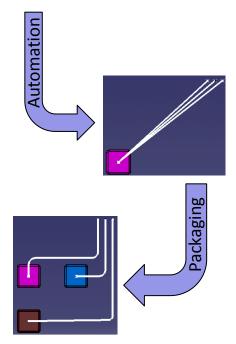
#### **Various Solutions**

- Reduce features in PowerCopy
  - Reduce grouping of different configurations into single PC
  - Automation utility to remove extra flexibility in the PCs after instantiation
  - Use of rules instead of Generative Shape Design (GSD) features



## **Further Enhancements**

Name	Start	End	Size
Connection.1	Key.1	Bus.1	2
Connection.2	Key.2	Bus.1	3
Connection.3	Key.3	Bus.1	2



- Startup Utility
  - Key / Connection info loaded from MS-Excel
  - All components positioned at origin with appropriate connections
- Edit Support
  - Edit key instances (not available with PC)
  - Insert points in connections to create chain of connections
- Packaging Validation
  - Check intersection between 3D Solids and Envelope
  - Violations provide 'immersive feedback'



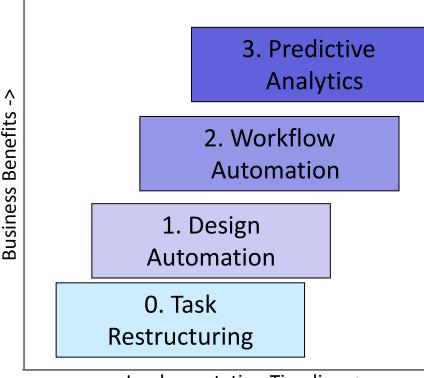
# Implementation & Results

#### Implementation Plan

- Duration 12-14 months
- Incremental implementation across multiple deployments
- Each phase signed-off by users, after a mockup / presentation.

### Results

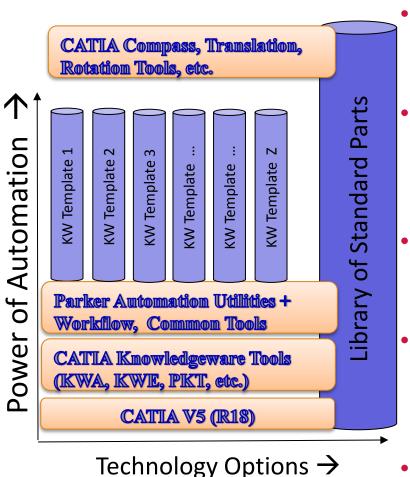
- Packaging effort reduced by ~50%
- Lead time reduced by ~40%
- Eases modifications & reuse due to better & uniform structure
- Rework due to clearance violations reduced significantly



#### Implementation Timeline ->



# Conclusion



- Generic architecture, extendable to a multidisciplinary control system
- OGS allowed managing a complex PC with various type of entities and multiple output as single unit
- Scalability issues can be tackled by optimizing no of features & use of rules
- Synergy of KW Templates with Automation Utilities enhances power of automation
- Incremental implementation approach achieved results with lower risk



## **Questions?**

#### Brian Prasad

Leader, Knowledge Engineering Team Parker Aerospace, Control Systems Division Irvine, California bprasad@parker.com

#### Nikhil Shintre

Technical Expert Geometric Limited Pune, India nikhil.shintre@geometricglobal.com